

Generalized Skew Derivation On (σ, τ) -Lie Ideals in Prime Rings

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Abstract: In the present paper, we extend some results concerning generalized skew derivation on (σ, τ) -Lie ideals of a prime rings.

Keywords: Prime ring, (σ, τ) -Lie ideal, generalized skew derivation, skew derivation.

1. INTRODUCTION

Throughout this paper, R is an associative ring, U a left ideal of R , $f : R \rightarrow R$ a generalized skew derivation associated with a nonzero skew derivation d and α an automorphism of R . A ring R is said to be prime ring, if for any $x, y \in R, xRy = 0$ implies that either $x = 0$ or $y = 0$ and is called semiprime ring if for any $x \in R, xRx = 0$ implies $x = 0$. An additive mapping $d : R \rightarrow R$ is said to be a derivation of R if for any $x, y \in R, d(xy) = d(x)y + xd(y)$. By a skew derivation of R we mean an additive map d from R into itself which satisfies the rule $d(xy) = d(x)y + \alpha(x)d(y)$ for all $x, y \in R$ and α being an automorphism of R . For $\alpha = 1$ is the identity automorphism of R , d is known as a derivation of R . In particular, for a fixed $a \in R$, the mapping $I_a : R \rightarrow R$ given by $I_a(x) = [x, a]$ is a derivation called an inner derivation of R . The commutativity of prime rings with derivation was initiated by E. C. Posner [18]. Over the last two decades, a great deal of work has been done on this subject. A function $f_{a,b} : R \rightarrow R$ is called a generalized inner derivation if $f_{a,b}(x) = ax + xb$ for some fixed $a, b \in R$. It is straightforward to note that $f_{a,b}$ is a generalized inner derivation, then for any $x, y \in R, f_{a,b}(xy) = f_{a,b}(x)y + x[y, b] = f_{a,b}(x)y + xI_b(y)$ where I_b is an inner derivation. In view of the above observation, the concept of generalized derivation is introduced in [15] and [8] as follows: An additive mapping $f : R \rightarrow R$ is called a generalized derivation associated with a derivation d if $f(xy) = f(x)y + xd(y)$ for all $x, y \in R$.

An additive mapping $G : R \rightarrow R$ is called a generalized inner derivation if $G(x) = ax + xb$, for fixed $a, b \in R$. For such a mappings $G(xy) = G(x)y + x[y, b] = G(x)y + xI_b(y)$, for all $x, y \in R$. Motivated by the above observation, Bresar introduced the concept of generalized derivation as

well as left multiplier mapping of R into R . The generalized derivation G of R is defined as an additive mapping $G : R \rightarrow R$ such that $G(xy) = G(x)y + xd(y)$ holds for any $x, y \in R$, where d is a derivation of R . So, every derivation is a generalized derivation, but the converse is not true in general. If $d = 0$, then we have $G(xy) = G(x)y$ for all $x, y \in R$, which is called a left multiplier mapping of R . Thus, generalized derivation generalizes both the concepts, derivation on R . An additive mapping $G : R \rightarrow R$ is said to be a (right) generalized skew derivation of R if there exists a skew derivation d of R with an associated automorphism α such that $G(xy) = G(x)y + \alpha(x)d(y)$ holds for all $x, y \in R$. For any two elements $x, y \in R, [x, y]$ will denote the commutator element $xy - yx$ and $[x, y]_{\sigma, \tau} = x\sigma(y) - \tau(y)x$ and $x\sigma y = xy + yx$. We use extensively the following basic commutator identities:

- i. $[xy, z] = x[y, z] + [x, z]y$
- ii. $[x, yz] = [x, y]z + y[x, z]$
- iii. $[xy, z]_{\sigma, \tau} = x[y, z]_{\sigma, \tau} + [x, \tau(z)]y = x[y, \sigma(z)] + [x, z]_{\sigma, \tau}y$
- iv. $[x, yz]_{\sigma, \tau} = \tau(y)[x, z]_{\sigma, \tau} + [x, y]_{\sigma, \tau}\sigma(z)$.

Let U be an additive subgroup of R . The definition of (σ, τ) -Lie ideal of R is given in [16] as follows:

- i. U is a (σ, τ) -right Lie ideal of R if $[U, R]_{\sigma, \tau} \subset U$.
- ii. U is a (σ, τ) -left Lie ideal of R if $[R, U]_{\sigma, \tau} \subset U$.
- iii. U is a (σ, τ) -Lie ideal of R , if U is both a (σ, τ) -right Lie ideal and (σ, τ) -left Lie ideal of R .

One may observe that the concept of generalized derivation includes the concept of derivations and generalized inner derivations, also of the left multipliers when $d = 0$. Hence it should be interesting to extend some results concerning these notions to generalized derivations. Some recent results were shown on generalized derivation in [8], [15] and [1].

Furthermore, some authors have also studied generalized derivation in the theory of operator algebras and C^* -algebras (see for example [15]). On the other hand, in [10, Definition 1], Golbasi and Kaya introduced the notation of right generalized derivation and left generalized derivation with associated derivation d as follows:

An additive mapping $f: R \rightarrow R$ is said to be right generalized derivation with associated derivation d if $f(xy) = f(x)y + xd(y)$ for all $x, y \in R$ and f is said to be left generalized derivation with associated derivation d if $f(xy) = d(x)y + xf(y)$ for all $x, y \in R$. An additive map f is said to be a generalized derivation with associated derivation d if it is both a left and right generalized derivation with associated derivation d . Of course, every derivation is generalized derivation and also, the definition of generalized derivation given in Bresar [8] is a right generalized derivation with associated derivation d according to above definition. In this context, we mention the definition of generalized derivation that means two sided generalized derivation.

In [1], Argac and Albas proved that if a prime ring R has $(d, \alpha), (g, \beta)$ nonzero generalized derivations such that $ad(x) = g(x)a$ for all $x \in R$, then one of the following possibilities holds; (i) $a \in C$ (extended centroid). (ii) There exist $p, q \in Q_r(R_C)$ (a right Martindale ring of quotients) such that $\alpha(x) = [x, p], \beta(x) = [q, x], qa \in C, p = \lambda a$, where $\lambda \in C$, for all $x \in R$. And the same result extended in [9], Ozgur Golbasi and Emine Koc for generalized derivations on (σ, τ) -left Lie ideal of R .

In [11], Herstein showed that if R is a prime ring of characteristic different from two and d is a nonzero derivation such that $d(R) \subset Z$, then R must be commutative. Several authors investigated this result for Lie ideals or (σ, τ) Lie ideals of a prime ring admitting derivation or generalized derivation (see [7], [6], [5], [9]). Ozgur Golbasi and Emine Koc proved extend some results on generalized derivations of semiprime rings in [2] and corresponding results for (σ, τ) -Lie ideal of a prime ring with generalized derivation [10]. Later on so many authors are extended the results for generalized (α, β) -derivation on ideals, Lie ideals in prime rings, semi prime rings. In [14], the author given some results on generalized (α, β) -derivation on Lie Ideals of σ -prime rings. Now our aim is to extend [10], Ozgur Golbasi and Emine Koc the results for generalized skew derivation on (σ, τ) -Lie ideal of a prime ring.

Throughout the present paper, we assume that R be a prime ring with characteristic not two, α, β, σ and τ are automorphisms and U a nonzero (σ, τ) -Lie ideal of R . We denote a generalized (α, β) -derivation f

$: R \rightarrow R$ with a non-zero (α, β) -derivation d of R by (f, d) . If $d = 0$, then $f(xy) = f(x)\alpha(y)$ for all $x, y \in R$ and there exists $q \in Q_r(R_C)$ such that $f(x) = qx$ for all $x \in R$ by [15, Lemma 2]. So, we assume that $d \neq 0$.

An additive mapping $f: R \rightarrow R$ is said to be right generalized (α, β) -derivation with associated non-zero (α, β) -derivation d if

$$(1.1) \quad f(xy) = f(x)\alpha(y) + \beta(x)d(y) \text{ for all } x, y \in R \text{ and } f \text{ is said to be left generalized } (\alpha, \beta) \text{-derivation with associated derivation } d \text{ if}$$

$$(1.2) \quad f(xy) = d(x)\alpha(y) + \beta(x)f(y) \text{ for all } x, y \in R.$$

f is said to be a generalized derivation with associated derivation d if it is both a left and right generalized derivation with associated derivation d .

2. PRELIMINARIES :

Lemma 1. [4, Lemma 3] *Let R be a prime ring with char $R \neq 2, a \in R$ and $aU = 0$ (or $Ua = 0$).*

- i. *If U is a (σ, τ) -right Lie ideal of R , then $a = 0$ or $U \subset C_{\sigma, \tau}$.*
- ii. *If U is a (σ, τ) -left Lie ideal of R , then $a = 0$ or $U \subset Z$.*

Lemma 2. [3, Lemma 6] *Let R be a prime ring with char $R \neq 2$ and U a (σ, τ) -left Lie ideal of R . Suppose there exists $a \in R$ such that $[a, U] = 0$. Then $a \in Z$ or $\sigma(u) + \tau(u) \in Z$ for all $u \in U$.*

Lemma 3. [13, Theorem 2] *Let R be a prime ring with char $R \neq 2$ and U a non-central (σ, τ) -left Lie ideal of R . Then there exist a nonzero ideal M of R such that $[R, M]_{\sigma, \tau} \subset U$ and $[R, M]_{\sigma, \tau} \not\subset C_{\sigma, \tau}$ or $\sigma(u) + \tau(u) \in Z$ for all $u \in U$.*

3. MAIN RESULTS

Theorem - 1 : *Let R be a prime ring with char $R \neq 2, f$ be a generalized skew derivation of R with a nonzero skew derivation d and an automorphism α of R and U a non-central (σ, τ) -left Lie ideal of R . If $f(U) = 0$, then $\sigma(u) + \tau(u) \in Z$ for all $u \in U$.*

Proof : Suppose to the contrary that $\sigma(u) + \tau(u) \notin Z$ for some $u \in U$. By Lemma 3, there exists a nonzero ideal M of R such that $[R, M]_{\sigma, \tau} \subset U$, but $[R, M]_{\sigma, \tau} \not\subset C_{\sigma, \tau}$. For any $x \in R$ and $m \in M, [x, m]_{\sigma, \tau} \sigma(m) = [x\sigma(m), m]_{\sigma, \tau} \in U$. Then $0 = f([x, m]_{\sigma, \tau} \sigma(m)) = f([x, m]_{\sigma, \tau} \sigma(m)) + \alpha([x, m]_{\sigma, \tau})d(\sigma(m))$ and so

$$(3.1) \quad \alpha([x, m]_{\sigma, \tau})d(\sigma(m)) = 0 \text{ for all } x \in R, m \in M.$$

Replacing x by $xy, y \in R$ in (3.1) and applying (3.1), we get $0 = \alpha([xy, m]_{\sigma, \tau})d(\sigma(m)) = \alpha(x[y, m]_{\sigma, \tau})d(\sigma(m)) + \alpha([x, \tau(m)]y)d(\sigma(m))$. That is, $\alpha([x, \tau(m)])d(\sigma(m)) = 0$ for all $x \in R, m \in M$. Since R is a prime ring, it

follows that $\alpha([x, \tau(m)]) = 0$ or $d(\sigma(m)) = 0$ for all $m \in M$. If $\alpha([x, \tau(m)]) = 0$, since α is an automorphism of R , applying α^{-1} on both sides we get $[x, \tau(m)] = 0$, hence $m \in Z$. We set $K = \{m \in M \mid m \in Z\}$ and $L = \{m \in M \mid d(\sigma(m)) = 0\}$. Clearly each of K and L is additive subgroup of M . Moreover, M is the set-theoretic union of K and L . But a group can not be the set-theoretic union of its two proper subgroups, hence $K = M$ or $L = M$. In the former case, $M \subset Z$ which forces R to be commutative. This is impossible because of $U \not\subset Z$. In the latter case, $d(\sigma(M)) = 0$. Since R is a prime ring and $\sigma(M)$ a nonzero ideal of R , we get $d = 0$, a contradiction. This completes the proof. \square

Theorem - 2 : Let R be a prime ring with $\text{char } R \neq 2$, f be a generalized skew derivation of R with a nonzero skew derivation d and α an automorphism of R and U a noncentral (σ, τ) -left Lie ideal of R . If $d(Z) \neq 0$ and $[f(U), a]_{\sigma, \tau} = 0$, then $a \in Z$ or $\sigma(u) + \tau(u) \in Z$ for all $u \in U$.

Proof: Choose $z \in Z$ such that $d(z) \neq 0$. It is easily seen that $d(z) \in Z$. For all $x \in R, u \in U$, we get

$$\begin{aligned} 0 &= [f([x, u]_{\sigma, \tau} z), a]_{\sigma, \tau} \\ &= [f([x, u]_{\sigma, \tau}) z + \alpha([x, u]_{\sigma, \tau}) d(z), a]_{\sigma, \tau} \\ &= [f([x, u]_{\sigma, \tau}), a]_{\sigma, \tau} z + f([x, u]_{\sigma, \tau}) [z, \sigma(a)] + [\alpha([x, u]_{\sigma, \tau}), a]_{\sigma, \tau} d(\alpha(z)) + \alpha([x, u]_{\sigma, \tau}) [d(\alpha(z)), \sigma(a)] \end{aligned}$$

and so $\alpha([x, u]_{\sigma, \tau}) d(z) = 0$ for all $x \in R, u \in U$. Since R is prime and $0 \neq d(z) \in Z$, we see that

$$(3.2) \quad \alpha([x, u]_{\sigma, \tau} a)_{\sigma, \tau} = 0 \text{ for all } x \in R, u \in U.$$

Substituting $x\sigma(u)$ for x in (3.2) and using this equation, we obtain $\alpha([x, u]_{\sigma, \tau}) \sigma([u, a]) = 0$ for all $x \in R, u \in U$. Now, taking xy instead of x in the last equation, we obtain $[R, \tau(u)] R \sigma([u, a]) = 0$ for all $u \in U$. Since R is a prime ring, it follows either $u \in Z$ or $[u, a] = 0$ for all $u \in U$. By a standard argument one of these must hold for all $u \in U$. If $u \in Z$ for all $u \in U$, then $U \subset Z$, and so $\sigma(u) + \tau(u) \in Z$ for all $u \in U$. If $[U, a] = 0$, then $a \in Z$ or $\sigma(u) + \tau(u) \in Z$ for all $u \in U$ by Lemma 2. Thus the proof is completed.

Theorem - 3 : Let R be a prime ring with $\text{char } R \neq 2$, $(f, d), (g, h)$ two generalized skew derivations of R and U a noncentral (σ, τ) -left Lie ideal of R . If $f(u)v = \alpha(u)g(v)$ for all $u, v \in U$, then $\sigma(u) + \tau(u) \in Z$ for all $u \in U$.

Proof : Suppose that $\sigma(u) + \tau(u) \notin Z$ for some $u \in U$. Then there exists a nonzero ideal M of R such that $[R, M]_{\sigma, \tau} \subset U$ and $[R, M]_{\sigma, \tau} \not\subset C_{\sigma, \tau}$ by Lemma 3. For any $x \in R$ and $m \in M, \tau(m)[x, m]_{\sigma, \tau} = [\tau(m)x, m]_{\sigma, \tau} \in U$. Taking $\tau(m)[x, m]_{\sigma, \tau}$ instead of u in the hypothesis, we get

$$\begin{aligned} f(\tau(m)[x, m]_{\sigma, \tau})v &= \alpha(\tau(m)[x, m]_{\sigma, \tau})g(v), \\ d(\tau(m)[x, m]_{\sigma, \tau})v + \alpha(\tau(m))f([x, m]_{\sigma, \tau})v &= \alpha(\tau(m)[x, m]_{\sigma, \tau})g(v). \end{aligned}$$

That is,

$$d(\tau(m)[x, m]_{\sigma, \tau})v + \alpha(\tau(m))\alpha([x, m]_{\sigma, \tau})g(v) = \alpha(\tau(m))\alpha([x, m]_{\sigma, \tau})g(v).$$

Hence we get, $d(\tau(m)[x, m]_{\sigma, \tau})v = 0$ for all $m \in M, v \in U, x \in R$. That is $d(\tau(m)[x, m]_{\sigma, \tau})U = (0)$ for all $m \in M, x \in R$. By Lemma 1, we obtain that

$$(3.3) \quad d(\tau(m)[x, m]_{\sigma, \tau}) = 0 \text{ for all } m \in M, x \in R.$$

Replacing x by $xy, y \in R$ in (2.3) and using (2.3), we have $d(\tau(m))x[y, \sigma(m)] = 0$ and so $d(\tau(m))R[y, \sigma(m)] = 0$ for all $m \in M, y \in R$. Since R is a prime ring, it follows that $m \in Z$ or $d(\tau(m)) = 0$ for all $m \in M$. Let $L = \{m \in M \mid m \in Z\}$ and $K = \{m \in M \mid d(\tau(m)) = 0\}$. By the same method in Theorem-1, we get $d = 0$, a contradiction. This completes the proof.

An immediately results of Theorem-3 we give the following corollaries.

Corollary - 1. Let R be a prime ring with $\text{char } R \neq 2$, $(f, d), (g, h)$ two generalized skew derivations of R and U a noncentral (σ, τ) -left Lie ideal of R . If $f(u)u = \alpha(u)g(u)$ for all $u \in U$, then $\sigma(u) + \tau(u) \in Z$ for all $u \in U$.

In particular if we take $f = g$, then we have the following corollary, which is a generalization of [13, Theorem] for the case when characteristic of underlying ring is different from two.

Corollary - 2. Let R be a prime ring with $\text{char } R \neq 2$, f is a generalized skew derivation of R and U a noncentral (σ, τ) -left Lie ideal of R . If $\alpha(u), f(u) = 0$ for all $u \in U$, then $\sigma(u) + \tau(u) \in Z$ for all $u \in U$.

Corollary - 3. Let R be a prime ring with $\text{char } R \neq 2$, d, h two nonzero skew derivations of R and U a noncentral (σ, τ) -left Lie ideal of R . If $d(u)v = \alpha(u)h(v)$ for all $u, v \in U$, then $\sigma(u) + \tau(u) \in Z$ for all $u \in U$.

Theorem - 4. Let R be a prime ring with $\text{char } R \neq 2$, U a noncentral (σ, τ) -left Lie ideal of R . Let $a, b \in R$ and $f: R \rightarrow R$ be a mapping such that $f(x) = xa - bx$ for all $x \in R$. If $f(U) \subset U$ and $f(U) \subset Z$, then $\sigma(u) + \tau(u) \in Z$ for all $u \in U$.

Proof : By the hypothesis, for all $u \in U$, we have $f(u) = ua - bu \in Z$. Commuting this element by u , we obtain that,

$$(3.4) \quad u[a, u] = [b, u]u \text{ for all } u \in U.$$

A linearization of (3.4) yields that $u[a, v] + v[a, u] = [b, v]u + [b, u]v$. Taking $f(u)$ instead of u in the above equation, we find that $f(u)[a, v] + v[a, f(u)] = [b, v]f(u) + [b, f(u)]v$. Using $f(u) \in Z$ in the last equation, we have

$$(3.5) \quad f(u)([a, v] - [b, v]) = 0 \text{ for all } u, v \in U.$$

Using the primeness of R and $f(u) \in Z$ in (2.5), we conclude that $f(U) = 0$ or $[a - b, U] = (0)$. If $[a - b, U] = (0)$, then $a - b \in Z$ or $\sigma(u) + \tau(u) \in Z$ for all $u \in U$ by

Lemma 2. Now, we assume that $a - b \in Z$. From (2.4), we obtain

$$(3.6) \quad u^2a - uau = ubu - bu^2 \text{ for all } u \in U.$$

Let $a - b = \alpha$, $\alpha \in Z$. Writing $a = b + \alpha$ in (2.6), we have $u^2b + u^2\alpha - ubu - u\alpha u = ubu - bu^2$ and $u^2b + u^2\alpha + bu^2 = 2ubu + u\alpha u$. Using $\alpha \in Z$ in the last equation, we get $u^2b + bu^2 - 2ubu = 0$, and $u^2b - ubu = ubu - bu^2$ and so $u[u, b] = [u, b]u$. That is $[u, [u, b]] = 0$ for all $u \in U$. This yields that $[u, d_b(u)] = 0$, where $d_b: R \rightarrow R$, $d_b(x) = [x, b]$ is an inner derivation of R . Therefore $\sigma(u) + \tau(u) \in Z$ for all $u \in U$ or $d_b = 0$ by Corollary 2. If $d_b = 0$, then $b \in Z$. We have $f(u) = ua - bu = u(a - b) \in Z$, by the hypothesis. Since $a - b \in Z$ and R is a prime ring, we obtain that $U \subset Z$ or $a - b = 0$. Now, we assume that $a = b$. Using $b \in Z$, we get $f(x) = xa - bx = xb - bx = 0$ for all $x \in U$. As a result $f = 0$, and so $f(U) = 0$. Hence $\sigma(u) + \tau(u) \in Z$ for all $u \in U$ according to Lemma 4. This completes the proof. \square

Corollary 4. Let R be a prime ring with $\text{char } R \neq 2$, U a nonzero (σ, τ) -Lie ideal of R and $a \in R$. If $[U, a]_{\sigma, \tau} \subset Z$, then $a \in Z$ or $\sigma(u) + \tau(u) \in Z$ for all $u \in U$.

Proof : Let f be a mapping such that $f(x) = [x, a]_{\sigma, \tau} = x\sigma(a) - \tau(a)x$ for all $x \in R$. Since U is a (σ, τ) -Lie ideal, we have $f(U) \subset U$. By Theorem 2, we get $\sigma(u) + \tau(u) \in Z$ for all $u \in U$. \square

Corollary 5. Let R be a prime ring with $\text{char } R \neq 2$, U a nonzero (σ, τ) -Lie ideal of R . If $[U, U]_{\sigma, \tau} \subset Z$, then $\sigma(u) + \tau(u) \in Z$ for all $u \in U$.

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